

A-priori and a-posteriori shock capturing technique for high order CAT schemes for systems of conservation laws

Workshop PRIN 2017

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# CAT scheme

Let us consider scalar conservation laws

$$u_t + f(u)_x = 0$$
  $u(x, t), x \in \mathbb{R}, t \ge 0.$ 

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For linear problems

$$u_t + au_x = 0$$

the generalized L-W method is given by

$$u_i^{n+1} = u_i^n + \sum_{k=1}^r \frac{\Delta t^k}{k!} u_i^{(k)},$$

where the equailities  $u_t = -au_x$  are used to approximate the time derivatives.

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where the equailities  $u_t = -au_x$  are used to approximate the time derivatives. This procedure can be extended to nonlinear systems by using the CK procedure Qui and Shu (2003) but the number of terms in the expression of the time derivatives increase exponentially.

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# CAT scheme

Zorio-Mulet-Baeza (2017) proposed the Approximate Taylor Method that using the Taylor approximations in time circumvented the Cauchy-Kovaleskya procedure

$$\partial_t^k u = -\partial_x^1 \partial_t^{k-1} f(u), \quad k = 1, 2 \dots r.$$

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The numerical methods obtained following the AT procedure of Zorio-Mulet-Baeza do not reduce to the LW methods for linear systems: they use (4P + 1)-point stencils instead of (2P + 1)-point ones.

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The numerical methods obtained following the AT procedure of Zorio-Mulet-Baeza do not reduce to the LW methods for linear systems: they use (4P + 1)-point stencils instead of (2P + 1)-point ones. Carrillo-Parés (2019) proposed the Compact Approximate Taylor Method that properly extend the LW methods. It needs a stencil of 2P + 1 points and a family of interpolatory formulas based on the 2P + 1 points.

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# CAT scheme

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-\frac{1}{2}}^P - F_{i+\frac{1}{2}}^P \right);$$

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# CAT scheme

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-\frac{1}{2}}^P - F_{i+\frac{1}{2}}^P \right);$$

### where

$$F_{i\pm\frac{1}{2}}^{P} = f_{i\pm\frac{1}{2}}^{(0)} + \frac{\Delta t}{2} f_{i\pm\frac{1}{2}}^{(1)} + \ldots + \frac{\Delta t^{2P-1}}{(2P)!} f_{i\pm\frac{1}{2}}^{(2P-1)}$$

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# CAT scheme

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-\frac{1}{2}}^P - F_{i+\frac{1}{2}}^P \right);$$

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in which,  $f_{i\pm\frac{1}{2}}^{(k)}$  is the k - th time derivative of f in position  $x_{i\pm\frac{1}{2}}$ .

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# CAT scheme

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-\frac{1}{2}}^P - F_{i+\frac{1}{2}}^P \right);$$

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in which,  $f_{i\pm\frac{1}{2}}^{(k)}$  is the k - th time derivative of f in position  $x_{i\pm\frac{1}{2}}$ .

$$f_{i+\frac{1}{2}}^{(k)} = \mathcal{I}\left(f_{i,-P+1}^{(k)}, \dots, f_{i,P}^{(k)}\right) = \sum_{j=-P+1}^{P} \gamma_{P,j}^{0,\frac{1}{2}} f_{i,j}^{(k)},$$
  
$$f_{i-\frac{1}{2}}^{(k)} = \mathcal{I}\left(f_{i,-P}^{(k)}, \dots, f_{i,P-1}^{(k)}\right) = \sum_{j=-P}^{P-1} \gamma_{P,j}^{0,\frac{1}{2}} f_{i,j}^{(k)}.$$

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# CAT scheme

 $f_{i,j}^{(k)} = \mathcal{D}_P^{k,j}\left(f_{i,j}^{k,*}, \Delta t\right) = \frac{1}{\Delta t^k} \sum_{r=-P+1}^{P} \gamma_{P,r}^{k,0} f_{i,j}^{k,n+r}$ 

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## CAT scheme

$$f_{i,j}^{(k)} = \mathcal{D}_{P}^{k,j}\left(f_{i,j}^{k,*}, \Delta t\right) = \frac{1}{\Delta t^{k}} \sum_{r=-P+1}^{P} \gamma_{P,r}^{k,0} f_{i,j}^{k,n+r}$$

where  $f_{i,j}^{k,n+r} = f(u_{i,j}^{k,n+r})$ 

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## CAT scheme

$$f_{i,j}^{(k)} = \mathcal{D}_P^{k,j}\left(f_{i,j}^{k,*}, \Delta t\right) = \frac{1}{\Delta t^k} \sum_{r=-P+1}^{P} \gamma_{P,r}^{k,0} f_{i,j}^{k,n+r}$$

where  $f_{i,j}^{k,n+r} = f(u_{i,j}^{k,n+r})$  and

$$u_{i,j}^{k,n+r} = u_{i+j}^n + \sum_{m=1}^k \frac{(r\Delta t)^m}{m!} u_{i,j}^{(m)}$$

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## CAT scheme

$$f_{i,j}^{(k)} = \mathcal{D}_{P}^{k,j}\left(f_{i,j}^{k,*}, \Delta t\right) = \frac{1}{\Delta t^{k}} \sum_{r=-P+1}^{P} \gamma_{P,r}^{k,0} f_{i,j}^{k,n+r}$$

where  $f_{i,j}^{k,n+r} = f(u_{i,j}^{k,n+r})$  and

$$u_{i,j}^{k,n+r} = u_{i+j}^n + \sum_{m=1}^k \frac{(r\Delta t)^m}{m!} u_{i,j}^{(m)}$$

with

$$u_{i,j}^{(k)} = -\mathcal{D}_P^{1,j}\left(f_{i,*}^{(k-1)}, \Delta x\right) = -\frac{1}{\Delta x} \sum_{s=-P+1}^{P} \gamma_{P,s}^{1,j} f_{i,s}^{(k-1)}$$

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# CAT scheme CAT2, P = 1

$$S_{i+\frac{1}{2}} = \{u_i^n, u_{i+1}^n\}$$
 and  $S_{i-\frac{1}{2}} = \{u_{i-1}^n, u_i^n\}$ 

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# CAT scheme CAT2, P = 1

$$\mathcal{S}_{i+\frac{1}{2}}=\{u_i^n,u_{i+1}^n\} \quad \text{and} \quad \mathcal{S}_{i-\frac{1}{2}}=\{u_{i-1}^n,u_i^n\}$$
 For all  $j=0,1$ 

$$u_{i,j}^{(1)} = -\frac{f_{i+1}^n - f_i^n}{\Delta x}$$
 and  $u_{i-1,j}^{(1)} = -\frac{f_i^n - f_{i-1}^n}{\Delta x}$ 

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# CAT scheme CAT2, P = 1

$$\mathcal{S}_{i+\frac{1}{2}}=\{u_i^n,u_{i+1}^n\} \quad \text{and} \quad \mathcal{S}_{i-\frac{1}{2}}=\{u_{i-1}^n,u_i^n\}$$
 For all  $j=0,1$ 

$$u_{i,j}^{(1)} = -\frac{f_{i+1}^n - f_i^n}{\Delta x}$$
 and  $u_{i-1,j}^{(1)} = -\frac{f_i^n - f_{i-1}^n}{\Delta x}$ 

$$f_{i,j}^{(1)} = \frac{f\left(u_{i+j}^{n} + \Delta t \, u_{i,j}^{(1)}\right) - f_{i+j}^{n}}{\Delta t}$$
$$f_{i-1,j}^{(1)} = \frac{f_{i+j}^{n} - f\left(u_{i-1+j}^{n} + \Delta t \, u_{i-1,j}^{(1)}\right)}{\Delta t}$$

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# CAT scheme CAT<sub>2</sub>, P = 1

$$f_{i+\frac{1}{2}}^{(1)} = \frac{1}{2} \left( f_{i,0}^{(1)} + f_{i,1}^{(1)} \right) \quad \text{and} \quad f_{i-\frac{1}{2}}^{(1)} = \frac{1}{2} \left( f_{i-1,0}^{(1)} + f_{i-1,1}^{(1)} \right)$$

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# CAT scheme CAT2, P = 1

$$f_{i+\frac{1}{2}}^{(1)} = \frac{1}{2} \left( f_{i,0}^{(1)} + f_{i,1}^{(1)} \right) \text{ and } f_{i-\frac{1}{2}}^{(1)} = \frac{1}{2} \left( f_{i-1,0}^{(1)} + f_{i-1,1}^{(1)} \right)$$

Finally,

$$\begin{split} F_{i-\frac{1}{2}}^{1} &= \frac{1}{2} \Big( \tilde{f}_{i-1,0}^{(0)} + \tilde{f}_{i-1,1}^{(0)} \Big) + \frac{\Delta t}{4} \Big( \tilde{f}_{i-1,0}^{(1)} + \tilde{f}_{i-1,1}^{(1)} \Big) = \\ &= \frac{1}{4} \left( f_{i-1}^{n} + f_{i}^{n} + f \left( u_{i-1}^{n} + \Delta t \, u_{i-1,0}^{(1)} \right) + f \left( u_{i}^{n} + \Delta t \, u_{i-1,1}^{(1)} \right) \right), \\ F_{i+\frac{1}{2}}^{1} &= \frac{1}{2} \Big( \tilde{f}_{i,0}^{(0)} + \tilde{f}_{i,1}^{(0)} \Big) + \frac{\Delta t}{4} \Big( \tilde{f}_{i,0}^{(1)} + \tilde{f}_{i,1}^{(1)} \Big) = \\ &= \frac{1}{4} \left( f_{i}^{n} + f_{i+1}^{n} + f \left( u_{i}^{n} + \Delta t \, u_{i,0}^{(1)} \right) + f \left( u_{i+1}^{n} + \Delta t \, u_{i,1}^{(1)} \right) \Big), \end{split}$$

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# CAT scheme CAT2, P = 1

$$f_{i+\frac{1}{2}}^{(1)} = \frac{1}{2} \left( f_{i,0}^{(1)} + f_{i,1}^{(1)} \right) \quad \text{and} \quad f_{i-\frac{1}{2}}^{(1)} = \frac{1}{2} \left( f_{i-1,0}^{(1)} + f_{i-1,1}^{(1)} \right)$$

Finally,

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$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-\frac{1}{2}}^1 - F_{i+\frac{1}{2}}^1 \right);$$

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### CAT scheme Properties

• High order one-step in space and time;

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- High order one-step in space and time;
- Conservative;

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- High order one-step in space and time;
- Conservative;
- Local reconstruction;

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- High order one-step in space and time;
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- CFL-1 stability condition;

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- High order one-step in space and time;
- Conservative;
- Local reconstruction;
- CFL-1 stability condition;
- Essentially oscillatory scheme.

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## ACAT

 $u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-1/2}^A - F_{i+1/2}^A \right),$ 

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## ACAT

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-1/2}^A - F_{i+1/2}^A \right),$$

where the flux is

$$F_{i+\frac{1}{2}}^{A} = \begin{cases} F_{i+1/2}^{p} & \text{if } \psi_{i+1/2}^{s} \approx 1, \quad s = P, \dots, p \\ F_{i+1/2}^{*} & \text{if } \psi_{i+1/2}^{p} << 1, \quad p = 2, \dots, P. \end{cases}$$

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## ACAT

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with

$$F_{i+1/2}^* = \varphi_{i+1/2}^1 F_{i+1/2}^1 + (1 - \varphi_{i+1/2}^1) F_{i+1/2}^{lo}.$$

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## ACAT

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-1/2}^A - F_{i+1/2}^A \right),$$

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in which

•  $F_{i+1/2}^{lo}$  is a first order robust numerical flux;

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$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-1/2}^A - F_{i+1/2}^A \right),$$

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in which

- $F_{i+1/2}^{lo}$  is a first order robust numerical flux;
- $F_{i+1/2}^1$  is the second order *CAT*<sup>2</sup> flux;

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## ACAT

$$u_i^{n+1} = u_i^n + \frac{\Delta t}{\Delta x} \left( F_{i-1/2}^A - F_{i+1/2}^A \right),$$

where the flux is

$$F_{i+\frac{1}{2}}^{A} = \begin{cases} F_{i+1/2}^{p} & \text{if } \psi_{i+1/2}^{s} \approx 1, \quad s = P, \dots, p \\ F_{i+1/2}^{*} & \text{if } \psi_{i+1/2}^{p} << 1, \quad p = 2, \dots, P. \end{cases}$$

with

$$F_{i+1/2}^* = \varphi_{i+1/2}^1 F_{i+1/2}^1 + (1 - \varphi_{i+1/2}^1) F_{i+1/2}^{lo}.$$

in which

*F*<sup>lo</sup><sub>i+1/2</sub> is a first order robust numerical flux; *F*<sup>1</sup><sub>i+1/2</sub> is the second order *CAT*2 flux; *F*<sup>P</sup><sub>i+1/2</sub> is the CAT flux of order 2*P*

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## ACAT Smoothness indicators

 $\varphi_{i+1/2}^1$  is an usual flux limiter function; Minmod, Superbee, Van Albada etc., see Toro, Kemm ,Leveque.
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 $\varphi_{i+1/2}^1$  is an usual flux limiter function; Minmod, Superbee, Van Albada etc., see Toro, Kemm ,Leveque.

How to estimate high order smooth indicators according the CAT method for p = 2, ..., P?

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## ACAT Smoothness indicators

 $\varphi_{i+1/2}^1$  is an usual flux limiter function; Minmod, Superbee, Van Albada etc., see Toro, Kemm ,Leveque.

How to estimate high order smooth indicators according the CAT method for p = 2, ..., P?

$$\psi_{i+1/2}^{p} = \left(\frac{\omega_{i+1/2}}{\omega_{i+1/2} + \tau_{p}}\right)^{2}$$

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## ACAT Smoothness indicators

 $\varphi_{i+1/2}^1$  is an usual flux limiter function; Minmod, Superbee, Van Albada etc., see Toro, Kemm ,Leveque.

How to estimate high order smooth indicators according the CAT method for p = 2, ..., P?

$$\psi_{i+1/2}^{p} = \left(\frac{\omega_{i+1/2}}{\omega_{i+1/2} + \tau_{p}}\right)^{2}$$
$$\omega_{i+1/2} = \frac{\omega_{i+\frac{1}{2}}^{L}\omega_{i+\frac{1}{2}}^{R}}{\omega_{i+\frac{1}{2}}^{L} + \omega_{i+\frac{1}{2}}^{R}},$$
$$L_{i+\frac{1}{2}} = \sum_{-p+1}^{-1} \left(f_{i+j+1}^{n} - f_{i+j}^{n}\right)^{2} + \xi, \quad \omega_{i+\frac{1}{2}}^{R} = \sum_{1}^{p-1} \left(f_{i+j+1}^{n} - f_{i+j}^{n}\right)^{2} + \xi.$$

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## MOOD CATMOOD paradigm



Figure: Left: Detection criteria of the MOOD technique for a candidate solution  $u_i^*$ . Computer Admissible Detector (CAD), Physical Admissible Detector (PAD) and Numerical Admissible Detector (PAD) — Right: Order cascades of CAT schemes used in the MOOD procedure. Starting from the most accurate one, CAT6, downgrading to lower order schemes, and, at last to a 1st order accurate scheme employed to ensure robustness.

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# Governing Equation 2D Euler

 $\partial_t U + \partial_x F(U) + \partial_y G(U) = 0$ 

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# Governing Equation 2D Euler

$$\partial_t U + \partial_x \mathsf{F}(U) + \partial_y \mathsf{G}(U) = 0$$

where

$$U = (\rho, \rho u, \rho v, \rho e)^t$$

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# Governing Equation 2D Euler

$$\partial_t U + \partial_x F(U) + \partial_y G(U) = 0$$

where

$$U = (\rho, \rho u, \rho v, \rho e)^t$$

and

$$\mathsf{F}(U) = \begin{pmatrix} \rho u \\ \rho u^2 + p \\ \rho uv \\ (\rho e + p)u \end{pmatrix}, \quad \mathsf{G}(U) = \begin{pmatrix} \rho v \\ \rho uv \\ \rho uv \\ \rho uv + p \\ (\rho e + p)v \end{pmatrix}$$

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# Governing Equation 2D Euler

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where

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and

$$\mathsf{F}(U) = \begin{pmatrix} \rho u \\ \rho u^2 + p \\ \rho uv \\ (\rho e + p)u \end{pmatrix}, \quad \mathsf{G}(U) = \begin{pmatrix} \rho v \\ \rho uv \\ \rho uv \\ \rho uv + p \\ (\rho e + p)v \end{pmatrix}$$

 $p = p(\rho, \varepsilon) = (\gamma - 1)(\rho e - \frac{1}{2} ||u||^2)$  which  $\gamma$  the adiabatic constant and u = (u, v).

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Isentropic Vortex Initial condition

## The computational domain is set to $\Omega = [-10, 10] \times [-10, 10]$ .

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### Isentropic Vortex Initial condition

The computational domain is set to  $\Omega = [-10, 10] \times [-10, 10]$ .  $\rho_{\infty} = 1.0$ ,  $u_{\infty} = 1.0$ ,  $v_{\infty} = 1.0$  and  $p_{\infty} = 1.0$ ,

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### Isentropic Vortex Initial condition

The computational domain is set to  $\Omega = [-10, 10] \times [-10, 10]$ .  $\rho_{\infty} = 1.0, u_{\infty} = 1.0, v_{\infty} = 1.0$  and  $p_{\infty} = 1.0, u_{\infty} = u_{\infty} + \delta u, v = v_{\infty} + \delta v, T^* = T^*_{\infty} + \delta T^*$ 

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### Isentropic Vortex Initial condition

The computational domain is set to  $\Omega = [-10, 10] \times [-10, 10]$ .  $\rho_{\infty} = 1.0, u_{\infty} = 1.0, v_{\infty} = 1.0$  and  $p_{\infty} = 1.0, u_{\infty} = u_{\infty} + \delta u, v = v_{\infty} + \delta v, T^* = T^*_{\infty} + \delta T^*$ 

$$\begin{split} \delta u &= -y' \frac{\beta}{2\pi} \exp\left(\frac{1-r^2}{2}\right), \delta v \quad = x' \frac{\beta}{2\pi} \exp\left(\frac{1-r^2}{2}\right), \\ \delta T &= -\frac{(\gamma-1)\beta^2}{8\gamma\pi^2} \exp\left(1-r^2\right), \end{split}$$

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### Isentropic Vortex Accuracy

| 2D Isentropic Vortex in motion - Rate of convergence |                       |       |                       |       |                       |          |                       |       |
|--|-----------------------|-------|-----------------------|-------|-----------------------|----------|-----------------------|-------|
|  | Rusanov-flux HLL      |       |                       | HLLC  |                       | CATMOOD6 |                       |       |
| N  | L <sup>1</sup> error  | order | L <sup>1</sup> error  | order | L <sup>1</sup> error  | order    | L <sup>1</sup> error  | order |
| 50 × 50  | 8.44×10 <sup>-3</sup> | _     | 8.44×10 <sup>-3</sup> | _     | 7.91×10 <sup>-3</sup> | -        | 8.48×10 <sup>-3</sup> |       |
| 100 $	imes$ 100                                      | 8.04×10 <sup>-3</sup> | 0.07  | 8.04×10 <sup>-3</sup> | 0.07  | 6.86×10 <sup>-3</sup> | 0.21     | 3.77×10 <sup>-3</sup> | 1.17  |
| $200 \times 200$                                     | 6.68×10 <sup>-3</sup> | 0.27  | 6.67×10 <sup>-3</sup> | 0.27  | 5.31×10 <sup>-3</sup> | 0.37     | 2.40×10 <sup>-7</sup> | 13.94 |
| $300 \times 300$                                     | 5.71×10 <sup>-3</sup> | 0.36  | 5.71×10 <sup>-3</sup> | 0.36  | 4.53×10 <sup>−3</sup> | 0.39     | 2.06×10 <sup>-8</sup> | 6.05  |
| $400 \times 400$                                     | 4.98×10 <sup>−3</sup> | 0.47  | 4.98×10 <sup>−3</sup> | 0.47  | 3.86×10 <sup>-3</sup> | 0.55     | 3.52×10 <sup>-9</sup> | 6.14  |
|  | Expected              | 1     | Expected              | 1     | Expected              | 1        | Expected              | 6     |
|  | CAT2                  |       | CAT4                  |       | CAT6                  |          | ACAT6                 |       |
| N  | L <sup>1</sup> error  | order | L <sup>1</sup> error  | order | L <sup>1</sup> error  | order    | L <sup>1</sup> error  | order |
| 50 × 50  | 7.94×10 <sup>-3</sup> | —     | 2.03×10 <sup>-3</sup> | —     | 8.46×10 <sup>-4</sup> | -        | 8.95×10 <sup>-3</sup> | _     |
| 100 $	imes$ 100                                      | 2.55×10 <sup>-3</sup> | 1.64  | 1.42×10 <sup>-4</sup> | 3.83  | 1.56×10 <sup>-5</sup> | 5.76     | 8.28×10 <sup>-3</sup> | 0.11  |
| $200 \times 200$                                     | 6.12×10 <sup>-4</sup> | 2.06  | 8.34×10 <sup>-6</sup> | 4.09  | 2.41×10 <sup>-7</sup> | 6.02     | 8.34×10 <sup>-5</sup> | 9.95  |
| $300 \times 300$                                     | 2.69×10 <sup>-4</sup> | 2.02  | 1.64×10 <sup>-6</sup> | 4.02  | 2.09×10 <sup>-8</sup> | 6.03     | 1.05×10 <sup>-5</sup> | 5.14  |
| $400 \times 400$                                     | 1.52×10 <sup>-4</sup> | 1.99  | 5.16×10 <sup>-7</sup> | 4.01  | 3.68×10 <sup>-9</sup> | 6.03     | 2.48×10 <sup>-6</sup> | 4.93  |
|  | Expected              | 2     | Expected              | 4     | Expected              | 6        | Expected              | 6     |

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### Isentropic Vortex CPU time



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# Sedov Blast Wave Density

The domain is given by  $(x, y) \in [-1.2, 1.2]^2$  initially  $(\rho^0, u^0, v^0, p^0, \gamma) = (1, 0, 0, 10^{-13}, 1.4)$ . A total energy of  $E_{total} = 0.244816$  is concentrated at the origin.

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# Sedov Blast Wave Scatter plot



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## 2D Riemann Initial condition

| Configuration 6             |                |                     |               |  |  |  |  |  |
|-----------------------------|----------------|---------------------|---------------|--|--|--|--|--|
| $\rho_2 = 2$                | $u_2 = 0.75$   | $ \rho_1 = 1.5 $    | $u_1 = 0.75$  |  |  |  |  |  |
| $v_2 = 0.5$                 | $p_{2} = 1$    | $v_1 = -0.5$        | $p_1=1$       |  |  |  |  |  |
| $\rho_3 = 1$                | $u_2 = -0.75$  | $ \rho_{4} = 3 $    | $u_4 = -0.75$ |  |  |  |  |  |
| <i>v</i> <sub>3</sub> = 0.5 | $p_{2} = 1$    | $v_4 = -0.5$        | $p_4=1$       |  |  |  |  |  |
| Configuration 11            |                |                     |               |  |  |  |  |  |
| $\rho_2 = 0.5313$           | $u_2 = 0.8276$ | $ ho_1 = 1$         | $u_1 = 0.1$   |  |  |  |  |  |
| $v_2 = 0$                   | $p_2 = 0.4$    | $v_1 = 0$           | $p_1=1$       |  |  |  |  |  |
| $\rho_3 = 0.8$              | $u_2 = 0.1$    | $\rho_4 = 0.5313$   | $u_4 = 0.1$   |  |  |  |  |  |
| $v_{3} = 0$                 | $p_2 = 0.4$    | $v_4 = 0$           | $p_4 = 0.4$   |  |  |  |  |  |
| Configuration 17            |                |                     |               |  |  |  |  |  |
| $\rho_2 = 2$                | $u_2 = 0.$     | $\rho_1 = 1$        | $u_1 = 0$     |  |  |  |  |  |
| $v_2 = -0.3$                | $p_2 = 1$      | $v_1 = -0.4$        | $p_1=1$       |  |  |  |  |  |
| $\rho_3 = 1.0625$           | $u_2 = 0$      | $ \rho_4 = 0.5197 $ | $u_{4} = 0$   |  |  |  |  |  |
| $v_3 = 0.2145$              | $p_2 = 0.4$    | $v_4 = -1.1259$     | $p_4 = 0.4$   |  |  |  |  |  |

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## 2D Riemann Configuration 6







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## 2D Riemann Configuration 11







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## 2D Riemann Configuration 17



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### Astrophysical jet Mach 2000

$$\Omega = [0, 1] \times [-0.25, 0.25], \, \gamma = 5/3$$

$$(\rho^{0}, u^{0}, v^{0}, p^{0}) = \begin{cases} (5, 800, 0, 0.4127) \\ (0.5, 0, 0, 0.4127) \end{cases}$$

if x = 0 and  $y \in [-0.05, 0.05]$ , otherwise,

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### Astrophysical jet Mach 2000

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# Conclusion

• Fully-discrete finite-difference one-step scheme

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- Fully-discrete finite-difference one-step scheme
- CFL-1 stability condition

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- Expected order

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# Conclusion

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Compat Approximate Taylor Scheme Shock Capturing Techniques 2D Numerical experiments Conclusion

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## Thanks for your attention